Game Theory taking over the world of PDEs

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Outline

Limit objects

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- Ø Homogenization in PDEs
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 - Parallel of frameworks
- Our contributions
 - Simple model
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Asymptotic value in games Homogenization in PDEs

GAMES

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Main research question

Question

What families of random games have a deterministic limit value?

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Example: Continuous weigthed reachability

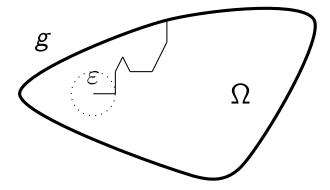


Figure 1: Continuous space reachability games

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Dynamic

Consider the following dynamic, indexed by $\varepsilon>0$

- State space is \mathbb{R}^n
- Domain $\Omega \subset \mathbb{R}^n$
- Reward function $g: \Omega^c \to \mathbb{R}$
- Initial position $x \in \Omega$
- Infinite random turn-based game
- At each turn, the corresponding player chooses where to move the state within $B(x, \varepsilon)$
- When arriving at $x \in \Omega^c$, min-player pays g(x) to the max-player

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Dynamic programming property

Let $u^{\varepsilon}: \Omega + B(0, \varepsilon) \to \mathbb{R}$ be the value. Then, for $x \in \Omega$,

$$u^{\varepsilon}(x) = \frac{1}{2} \left(\sup_{y \in B(x,\varepsilon)} u^{\varepsilon}(y), \inf_{y \in B(x,\varepsilon)} u^{\varepsilon}(y) \right)$$

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Asymptotic value

In this game,

$$(u^{\varepsilon}) \xrightarrow[\varepsilon \to 0]{\varepsilon \to 0} u$$
,

such that u is the solution of

$$\begin{cases} \Delta_{\infty} u(x) = \sum_{i,j} \partial_{i,j}^2 u(x) \partial_i u(x) \partial_j u(x) = 0 & x \in \Omega \\ u(x) = g(x) & x \in \partial \Omega \end{cases}$$

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Research question

Question

What games in \mathbb{R}^n have an asymptotic value?

The previous example shows that weigthed reachability has an asymptotic value.

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Algorithmic perspective

For each $\varepsilon > 0$, this game is discrete in time and continuous in space.

Question

Is there a space discretization with probable approximation of the limit value function?

Answering this question requires proving rate of convergence in both continuous and discrete time settings.

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PDEs

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Example: Heat equation

Consider the heat equation.

$$\begin{cases} \partial_t u(t,x) - \Delta u(t,x) = \partial_t u(t,x) - \sum_i \partial_{i,i}^2 u(t,x) = 0 & x \in \Omega \\ u(0,x) = u_0(x) & x \in \Omega \end{cases}$$

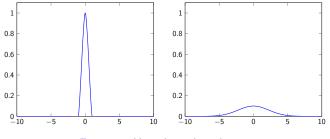


Figure 2: Heat kernel evolution

Heat equation in heterogeneous media

Consider the heat equation in a media.

$$\begin{cases} \partial_t u - \nabla (A \nabla u) = \partial_t u - \sum_i \partial_i \sum_j A_{i,j} \partial_j u = 0 & x \in \Omega \\ u(0, x) = u_0(x) & x \in \Omega \end{cases}$$



Figure 3: Heterogeneous periodic media

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Heat equation: Homogenization limit

Consider the heat equation in a limit media. Let $\varepsilon > 0$,

$$\begin{cases} \partial_t u^{\varepsilon} - \nabla (A(x/\varepsilon)\nabla u^{\varepsilon}) = \partial_t u - \sum_i \partial_i \sum_j A_{i,j}(x/\varepsilon) \partial_j u^{\varepsilon} = 0 & x \in \Omega \\ u^{\varepsilon}(0,x) = u_0(x) & x \in \Omega \end{cases}$$

And consider the limit of u_{ε} , as $\varepsilon \to 0$.

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Homogenization definition

Let $H: \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$ be a "hamiltonian". Define, for $\varepsilon > 0$,

$$\begin{cases} \partial_t u^{\varepsilon} + H(\nabla u^{\varepsilon}, x/\varepsilon) = 0 & x \in \Omega \\ u^{\varepsilon}(0, x) = u_0(x) & x \in \Omega \end{cases}$$

Definition (Homogenization)

The hamiltonian H presents homogenization if there is an effective hamiltonian \overline{H} such that $(u^{\varepsilon}) \xrightarrow[\varepsilon \to 0]{} u$, where u is the solution of

$$\begin{cases} \partial_t u + \overline{H}(\nabla u) = 0 & x \in \Omega \\ u(0, x) = u_0(x) & x \in \Omega \end{cases}$$

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Homogenization question

Question

What Hamiltonians do homogenize?

Theorem (Sufficient conditions)

If H is periodic in the space variable, H homogenizes.

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Stochastic homogenization

Since random medias are "periodic", consider now a random hamiltonian.

Definition (Stochastic Homogenization)

The random hamiltonian H presents homogenization if there is an *effective* hamiltonian \overline{H} such that $(U^{\varepsilon}) \xrightarrow[\varepsilon \to 0]{} u$, where u is the (deterministic) solution of

$$\begin{cases} \partial_t u + \overline{H}(\nabla u) = 0 & x \in \Omega \\ u(0, x) = u_0(x) & x \in \Omega \end{cases}$$

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Stochastic Homogenization question

Question

What random Hamiltonians present stochastic homogenization?

Theorem (Sufficient conditions)

Under standard assumptions on H and **convexity** on the space variable, H has stochastic homogenization.

Theorem (Tightness on convexity)

There exists H astisfying standard assumptions but not convexity on the space variable, such that H does not have stochastic homogenization.

GAMES and PDEs

Game values and Hamiltonians

In (random) games, we ask if

$$(V^{\varepsilon}) \xrightarrow[\varepsilon \to 0]{\varepsilon \to 0} v.$$

In stochastic homogenization, we ask if

$$(H(\nabla u^{\varepsilon}, x/\varepsilon)) \xrightarrow[\varepsilon \to 0]{} \overline{H}(\nabla u).$$

Given a hamiltonian H, one may construct a game where the solution u^{ε} is the value of the game.

Question

Which hamiltonians have a game-theoretical interpretation?

Parallel frameworks

Main research question

Question

What families of random games have a deterministic limit value?

Simple model Results so far

GAMES in the plane

Simple model Results so far

Random game on the plane

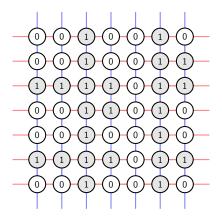


Figure 4: Average payoff game in random media

Simple model Results so far

Dynamic

Consider the following dynamic, indexed by $\varepsilon>0$

- $\bullet\,$ State space is \mathbb{Z}^2
- Random reward function $G \colon \mathbb{Z} \to \mathbb{R}$, where $G(z) \sim B(p)$, for $p \in [0,1]$
- Initial state is (0,0)
- Infinite turn-based game
- At each turn, the corresponding player chooses where to move the state:
 - Max-player chooses up or down
 - Min-player chooses *left* or *right*
- The reward is the discounted average

$$\varepsilon \sum_{n\in\mathbb{N}} (1-\varepsilon)^n G(z_n).$$

If you restrict the player to move in one direction, i.e. a state is never visited again, then [GZ21] show that (V^{ϵ}) converges to a deterministic limit.

The general framework is still open.

Question

Is there a limit value? Is the limit a constant?

Simple model Results so far

Percolation thresholds

Theorem

There exists $0 < p_0 < p_1 < 1$ such that

$$egin{array}{lll} (\mathcal{V}^arepsilon) & \longrightarrow & 0 & & orall p < p_0 \ (\mathcal{V}^arepsilon) & \longrightarrow & 1 & & orall p > p_1 \end{array}$$

Simple model Results so far

References I

Guillaume Garnier and Bruno Ziliotto. Percolation games. 2021.

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